

passages connecting the first internal corridor to the second internal corridor, wherein the UAV service sites are located within the UAV passages.

**15.** The multi-level structure as recited in claim 6, wherein the UAV service sites are further configured to:  
charge or replace a battery of a UAV, and  
couple a package to the UAV.

**16.** The multi-level structure as recited in claim 6, further comprising a launch assist mechanism configured with the UAV service site, the launch assist mechanism to provide a trajectory force to a UAV during a launch of the UAV from the UAV service site.

**17.** A multi-level unmanned aerial vehicle (UAV) landing structure comprising:

an exterior shell that includes coupling features extending outward from the exterior shell; and

UAV platforms to support landings and takeoffs of the UAVs, the UAV platforms coupled to the exterior shell, and the UAV platforms including a plurality of arms that selectively engage the coupling features and move the UAV platforms relative to the coupling features and about the exterior shell.

**18.** The multi-level UAV landing structure as recited in claim 17, wherein the coupling features include power coupling components to provide power to the UAV platform as the UAV platform moves about the coupling features.

**19.** The multi-level UAV landing structure as recited in claim 17, further comprising apertures located in the exterior shell, the apertures to selectively open in response to positioning of a UAV platform proximate to an aperture.

**20.** The multi-level UAV landing structure as recited in claim 17, wherein the UAV platform includes a controller to move the UAV platform about the exterior shell while avoiding conflicts with other UAV platforms.

**21.** The multi-level UAV landing structure as recited in claim 17, wherein the UAV platform is configured to raise a UAV readied for deployment to a higher location on the exterior shell than a location of a coupling of a package to the UAV.

**22.** The multi-level structure as recited in claim 6, further comprising an internal transport robot to move a UAV within the interior of the multi-level structure and to charge a power source of the UAV.

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